ON THE BUCKLING MODES AND BUCKLING LOAD OF AN INFINITELY LONG BUT HARMONICALLY IMPERFECT COLUMN LYING ON CUBIC – QUINTIC FOUNDATION.

ABSTRACT

This paper utilizes perturbation and asymptotic techniques to dismiss and obtain, analytically, the buckling modes and buckling load of a harmonically imperfect column lying on an elastic foundation that has cubic – quintic nonlinearity. Two slightly different approaches are here utilized. In the first approach, the perturbation parameter is a component of the displacement while in the second approach, the perturbation is a component of the load. In the final assessment, results from both approaches are seen to be in good agreement. The results are however observed to be implicit in the load parameter and are valid asymptotically as long as these perturbation parameters are small relative to unity.

KEYWORDS: Infinitely Long Columns, Nonlinear Elastic Foundation, Static Buckling, Perturbation Technique, Asymptotic Analysis.

1. INTRODUCTION

In this paper, a perturbation scheme in asymptotic series expansions, is developed in determining the static buckling load and buckling modes of an infinitely long but harmonically imperfect column lying on a cubic – quintic nonlinear elastic foundation, where the column is trapped by a static load of magnitude P. It is to be recalled that, as far as investigations concerning columns are concerned, majority of the existing research findings have tended to favour columns lying on nonlinear cubic elastic foundations [1, 2, 3] to the exclusion of most other nonlinear elastic foundations. In this study, we intend to stretch the analysis to the case where the foundation has a cubic – quintic nonlinearity.

Generally, investigations on buckling, both static and dynamic, have tended to attract and occupy a prominent attention amongst the research community for a long time now. In this respect, mention is here made of investigation by Reda and Forbes [4], Priyadarsini et al. [5], Chitra and Priyadarsini [6], Mcshane et al. [7], Kolakowski [8, 9] and Patil et al. [10], among others.

2. GOVERNING EQUATION

The normal displacement W(X) of the column, subjected to the applied load P, satisfies the non – homogeneous equation

$$EI\frac{d^4W}{dX^4} + 2P\frac{d^2W}{dX^2} + k_1W + \alpha k_2W^3 - \beta_1k_3W^5 = -2P\frac{d^2\bar{W}}{dX^2}, \quad -\infty < X < \infty$$
(2.1)

where X is the spatial coordinate, EI is the bending stiffness , where E and I are the Young's modulus and moment of inertia respectively and \overline{W} is the twice differentiable stress – free harmonic imperfection. The cubic – quintic nonlinear elastic foundation exerts a force per unit length given by $k_1W + \alpha k_2W^3 - \beta_1k_3W^5$ on the column, while α and β_1 are the imperfection – sensitivity factors which are to be carefully chosen so that the column becomes imperfection – sensitive and k_1 , k_2 and k_3 are positive constants. In this formulation, we have neglected all nonlinearities greater than quintic while all nonlinear derivatives are neglected.

In order to nondimensionalize the equation, the following nondimensional quantities are now assumed.

$$X = \left(\frac{EI}{k_1}\right)^{\frac{1}{4}} x, \quad W = \left(\frac{k_1}{k_2}\right)^{\frac{1}{2}} w, \quad \overline{W} = \epsilon \left(\frac{k_1}{k_2}\right)^{\frac{1}{2}} \overline{w}, \quad \beta = \left(\frac{\beta_1 k_1 k_3}{k_2^2}\right), \quad P = 2\lambda (EIk_1)^{\frac{1}{2}}$$

Here, ϵ and λ satisfy the inequalities $0 < \epsilon \ll 1, 0 < \lambda < 1$, and the nondimensional form of the equation is

$$\frac{d^4w}{dx^4} + 2\lambda \frac{d^2w}{dx^2} + w + \alpha w^3 - \beta w^5 = -2\lambda \epsilon \frac{d^2\overline{w}}{dx^2}, \quad -\infty < x < \infty$$
(2.2)

We shall solve the equation in two slightly different approaches whereby, in the first approach, we adopt the perturbation and asymptotic parameter as a component of displacement whereas in the second approach, we adopt the perturbation parameter as a component of the applied load. In this latter case, we shall let $= 1 - \frac{\overline{\epsilon}^2}{2}$, for $0 < \overline{\epsilon} \ll 1$, where λ is the nondimensional load amplitude. In both cases, we aim at first determining a uniformly valid asymptotic expression of the normal displacement subsequent upon which the static buckling load, λ_s , is next determined. The static buckling load λ_s , as in [1 - 3], is defined as the maximum value of the load amplitude λ that emanates from the origin of the load – displacement graphical configuration of the loading system.

3. SOLUTION OF (2.2) USING DISPLACEMENT AS PERTURBATION PARAMETER

Since the imperfection is harmonic, we let

$$\overline{w} = \cos nx, \qquad n = 1, 2, 3, ...$$
 (3.1)

Assuming that the displacement must be in the shape of imperfection, we let

$$w(x) = \cos nx, \tag{3.2}$$

The equation satisfied by the perfect linear structure is

$$\frac{d^4w}{dx^4} + 2\lambda \frac{d^2w}{dx^2} + w = 0$$
(3.3)

The resultant equation when (3.2) is substituted in (3.3) is

$$(n^4 - 2n^2\lambda + 1) = 0, \quad \lambda = \frac{1}{2n^2}(n^4 + 1)$$
 (3.4)

The least value of λ in (3.4) is obtained when n = 1 and for this the classical buckling load λ_{c} is

$$\lambda_{\rm C} = 1 \tag{3.5}$$

For the solution of (2.2), it is necessary to let

$$w(x) = \bar{\varepsilon} \cos x + v(x) \tag{3.6}$$

It is here assumed that the average value of $v(x) \cos x$ vanishes over the interval of definition of x, that is

$$\langle v(x)cosx \rangle = 0 \tag{3.7}$$

where, $< \cdots >$ denotes the average of v(x)cosx. Thus, with w known, $\bar{\varepsilon}$ is uniquely defined.

Let

$$v(x) = \sum_{m=2}^{\infty} \bar{\varepsilon}^m v_m, \qquad \lambda \epsilon = \sum_{m=1}^{\infty} \bar{\varepsilon}^m Q_m$$
(3.8)

In order to solve (2.2), using (3.2), equations (3.8) are now substituted into (2,2) and thereafter, we equatte the coefficients of powers of $\bar{\varepsilon}$ to get

$$\boldsymbol{O}(\bar{\varepsilon}): \quad 2(1-\lambda)\cos x = 2Q_1\cos x \tag{3.9}$$

$$\boldsymbol{O}(\bar{\varepsilon}^2): \ Mv_2 \equiv \ \frac{d^4v_2}{dx^4} + 2\lambda \frac{d^2v_2}{dx^2} + \ v_2 = 2Q_2 \cos x \tag{3.10}$$

$$\boldsymbol{0}(\bar{\varepsilon}^3): \ M v_3 = 2Q_3 \cos x - \alpha \cos^3 x \tag{3.11}$$

$$\boldsymbol{0}(\bar{\varepsilon}^4): \ Mv_4 = 2Q_4\cos x - 3\alpha v_2\cos^2 x \tag{3.12}$$

$$\boldsymbol{0}(\bar{\varepsilon}^5): \ Mv_5 = 2Q_5\cos x - 3\alpha v_3\cos^2 x - 3\alpha v_2\cos x + \beta\cos^5 x$$
(3.13)

$$\boldsymbol{0}(\bar{\varepsilon}^6): \ Mv_6 = 2Q_6\cos x - 3\alpha v_2\cos^4 x - 6\alpha v_2 v_3\cos x + 5\beta v_2\cos^4 x$$
(3.14)

$$\boldsymbol{O}(\bar{\varepsilon}^7): \ Mv_7 = 2Q_7 \cos x - \alpha [3v_5 \cos^2 x + 6v_2 v_4 \cos x + 3v_3^2 \cos x] + \beta v_3 \cos^4 x$$
(3.15)

etc.

From (3.9), it is easily seen that

$$Q_1 = (1 - \lambda), \quad v_1 = 0$$
 (3.16)

On using the condition (3.7), it is seen that

$$Q_2 = 0, \quad v_2$$
 (3.17)

On simplification, equation (3.11) becomes

$$Mv_3 = \left(2Q_3 - \frac{3\alpha}{4}\right)\cos x - \frac{\alpha}{4}\cos 3x \tag{3.18}$$

On using the condition (3.7) on (3.18), it easily follows that

$$Q_3 = \frac{3\alpha}{8} \tag{3.19}$$

After solving the remaining equation in (3.18), we have

$$v_3 = \frac{-\alpha \cos 3x}{8(41 - 9\lambda)} \tag{3.20}$$

From (3.12), it easily follows that

$$Q_4 = v_4 = 0 \tag{3.21}$$

Equation (3.13) is next simplified to yield (using (3.17))

$$Mv_{5} = \left(2Q_{5} + \frac{5\beta}{8} + \frac{3\alpha^{2}}{32(41 - 9\lambda)}\right)\cos x + \left(\frac{15\beta}{16} + \frac{3\alpha^{2}}{16(41 - 9\lambda)}\right)\cos 3x + \left(\frac{\beta}{16} + \frac{3\alpha^{2}}{32(41 - 9\lambda)}\right)\cos 5x$$
(3.22)

On applying (3.7) in (3.22), this yields

$$Q_5 = -\frac{1}{2} \left(\frac{5\beta}{8} + \frac{3\alpha^2}{32(41 - 9\lambda)} \right)$$
(3.23)

The solution of the remaining equation in (3.22) is

$$v_{5} = \frac{1}{32} \left(\beta + \frac{3\alpha^{2}}{(41 - 9\lambda)}\right) \left(\frac{\cos 3x}{(41 - 9\lambda)}\right) + \frac{1}{64} \left(2\beta + \frac{3\alpha^{2}}{(41 - 9\lambda)}\right) \left(\frac{\cos 5x}{(313 - 25\lambda)}\right) \quad (3.24)$$

After substituting in (3.14), we get

$$Q_6 = v_6 = 0 \tag{3.25}$$

Next, we substitute in (3.15) and simplify to get

$$Mv_{7} = \left[2Q_{7} - \frac{3\alpha}{2}\left\{\frac{A_{1}}{2} + \frac{\alpha^{2}}{128(41 - 9\lambda)^{2}}\right\} + \frac{5\beta}{8}\right]\cos x + \left[\frac{3\beta}{8} - \frac{3\alpha}{2}\left(A_{1} + \frac{A_{2}}{2}\right)\right]\cos 3x + \left[\frac{\beta}{2} - \frac{3\alpha}{2}\left\{\left(A_{2} + \frac{A_{1}}{2}\right) + \frac{\alpha^{2}}{256(41 - 9\lambda)^{2}}\right\}\right]\cos 5x + \left[\frac{\beta}{8} - \frac{3\alpha}{2}\left\{\frac{A_{2}}{2} + \frac{\alpha^{2}}{256(41 - 9\lambda)^{2}}\right\}\right]\cos 7x \qquad (3.26a)$$

where,

$$A_{1} = \frac{1}{32(41 - 9\lambda)} \left(\beta + \frac{3\alpha^{2}}{41 - 9\lambda}\right)$$
(3.26*b*)

$$A_2 = \frac{1}{64(313 - 25\lambda)} \left(2\beta + \frac{3\alpha^2}{41 - 9\lambda} \right)$$
(3.26c)

The condition (3.7) as applied to (3.26a) yields

$$Q_7 = \frac{1}{2} \left[\frac{3\alpha}{2} \left\{ \frac{A_1}{2} + \frac{\alpha^2}{128(41 - 9\lambda)^2} \right\} \right] - \frac{5\beta}{8}$$
(3.26*d*)

The solution of the remaining equation in (3.26a) yields

$$v_{7} = \frac{1}{2} \left[\frac{3\beta}{8} - \frac{3\alpha}{2} \left(A_{1} + \frac{A_{2}}{2} \right) \right] \left(\frac{\cos 3x}{41 - 9\lambda} \right) + \frac{1}{2} \left[\frac{\beta}{2} - \frac{3\alpha}{2} \left(A_{2} + \frac{A_{1}}{2} + \frac{\alpha^{2}}{256(41 - 9\lambda)^{2}} \right) \right] \left(\frac{\cos 5x}{313 - 25\lambda} \right) \\ + \frac{1}{2} \left[\frac{\beta}{8} - \frac{3\alpha}{2} \left\{ \frac{A_{2}}{2} + \frac{\alpha^{2}}{256(41 - 9\lambda)^{2}} \right\} \right] \left(\frac{\cos 7x}{1201 - 49\lambda} \right)$$
(3.27)

Following (3.6), we can now write

$$w = \bar{\varepsilon} \cos x - \frac{\alpha \bar{\varepsilon}^{3} \cos 3x}{8(41 - 9\lambda)} + \bar{\varepsilon}^{5} \left[\frac{1}{32} \left(\beta + \frac{3\alpha^{2}}{41 - 9\lambda} \right) \left(\frac{\cos 3x}{41 - 9\lambda} \right) + \frac{1}{64} \left(2\beta + \frac{3\alpha^{2}}{41 - 9\lambda} \right) \left(\frac{\cos 5x}{313 - 25\lambda} \right) \right] + \frac{\bar{\varepsilon}^{7}}{2} \left[\left[\frac{3\beta}{8} - \frac{3\alpha}{2} \left(A_{1} + \frac{A_{2}}{2} \right) \right] \left(\frac{\cos 3x}{41 - 9\lambda} \right) + \left[\frac{\beta}{2} - \frac{3\alpha}{2} \left(A_{2} + \frac{A_{1}}{2} + \frac{\alpha^{2}}{256(41 - 9\lambda)^{2}} \right) \right] \left(\frac{\cos 5x}{313 - 25\lambda} \right) + \left[\frac{\beta}{8} - \frac{3\alpha}{2} \left\{ \frac{A_{2}}{2} + \frac{\alpha^{2}}{256(41 - 9\lambda)^{2}} \right\} \right] \left(\frac{\cos 7x}{1201 - 49\lambda} \right) \right] + \cdots$$
(3.28)

Similarly, we have (from (3.8))

$$\lambda \epsilon = \bar{\epsilon}(1-\lambda) + \frac{3\alpha \bar{\epsilon}^3}{8} - \frac{\bar{\epsilon}^5}{2} \left(\frac{5\beta}{8} + \frac{3\alpha^2}{32(41-9\lambda)} \right) + \frac{\bar{\epsilon}^7}{2} \left[\frac{3\alpha}{2} \left\{ \frac{A_1}{2} + \frac{\alpha^2}{128(41-9\lambda)^2} \right\} - \frac{5\beta}{8} \right] + \cdots$$
(3.29)

To determine the static buckling load λ_S , we, as in [1 – 3], use the condition

$$\frac{d\lambda}{d\varepsilon} = 0, \tag{3.30}$$

and get

$$(1 - \lambda_S) + \frac{9\alpha \bar{\varepsilon}_S^2}{8} - \frac{5\bar{\varepsilon}_S^4}{2} \left(\frac{3\alpha^2}{32(41 - 9\lambda)} + \frac{5\beta}{8} \right) = 0$$
(3.31)

On solving, this yields

$$\bar{\varepsilon}_{S}^{2} = \frac{9\alpha}{40\left\{\frac{3\alpha^{2}}{32(41-9\lambda_{S})} + \frac{5\beta}{8}\right\}} \left[1 - \sqrt{1 + \frac{512(1-\lambda_{S})}{405\alpha^{2}\left\{\frac{3\alpha^{2}}{32(41-9\lambda_{S})} + \frac{5\beta}{8}\right\}}}\right]$$
(3.32)

and

$$\therefore \quad \bar{\varepsilon}_{S} = \frac{3}{2\sqrt{10}} \sqrt{\frac{\alpha}{40\left\{\frac{3\alpha^{2}}{32(41-9\lambda_{S})} + \frac{5\beta}{8}\right\}}} \left[1 - \left\{1 + \frac{512(1-\lambda_{S})}{405\alpha^{2}\left\{\frac{3\alpha^{2}}{32(41-9\lambda_{S})} + \frac{5\beta}{8}\right\}}\right\}^{\frac{1}{2}}\right]^{\frac{1}{2}} \quad (3.33)$$

The static buckling load λ_s is now obtained by evaluating (3.29) at $\lambda = \lambda_s$ and substituting for $\bar{\epsilon}_s^2$ and $\bar{\epsilon}_s$ from (3.32) and (3.33) respectively and this yields

$$\lambda_{S}\epsilon = \bar{\epsilon}_{S}\left[(1 - \lambda_{S}) + \bar{\epsilon}_{S}^{2} \left\{ \left\{ \frac{3\alpha}{8} - \bar{\epsilon}_{S}^{2} \left(\frac{3\alpha^{2}}{32(41 - 9\lambda_{S})} + \frac{5\beta}{8} \right) + \frac{\bar{\epsilon}_{S}^{2}}{2} \left\{ \frac{3\alpha}{2} \left(\frac{A_{1}}{2} + \frac{\alpha^{2}}{128(41 - 9\lambda)^{2}} \right) - \frac{5\beta}{8} \right\} \right\} \right]$$
(3.34)

4. SOLUTION OF (2.2) WITH LOAD COMPONENT AS PERTURBATION PARAMETER

Here, we shall let

$$\lambda = 1 - \frac{\varepsilon^2}{2}, \quad 0 < \varepsilon < 1 \tag{4.1}$$

In this case, equation (2.2) becomes

$$\frac{d^4w}{dx^4} + 2\frac{d^2w}{dx^2} - \varepsilon^2 \frac{d^2w}{dx^2} + w + \alpha w^3 - \beta w^5 = -2\lambda \epsilon \frac{d^2\overline{w}}{dx^2}$$
(4.2)

Let

$$w(x) = \bar{b}\varepsilon \cos x + u(x), \qquad 0 < \bar{b} < 1 \tag{4.3}$$

Further let

$$u(x) = \sum_{m=2}^{\infty} \varepsilon^m u_m, \qquad \lambda \epsilon = \sum_{m=1}^{\infty} \varepsilon^m \gamma_m$$
(4.4)

Substituting for terms in (4.2) and equating the coefficients of powers of ε , yields

$$\boldsymbol{O}(\varepsilon): \ Nu_1 \equiv \frac{d^4 u_2}{dx^4} + 2\lambda \frac{d^2 u_2}{dx^2} + u_2 = 2\gamma_1 \cos x \tag{4.5}$$

$$\boldsymbol{0}(\varepsilon^2): \quad Nu_2 = 2\gamma_2 \cos x \tag{4.6}$$

$$\boldsymbol{0}(\varepsilon^3): \quad Nu_3 = -\bar{b}\cos x - \alpha \bar{b}^3 \cos^3 x + 2\gamma_3 \cos x \tag{4.7}$$

$$\boldsymbol{O}(\varepsilon^4): \ Nu_4 = \frac{d^2 u_2}{dx^2} - 3\bar{b}^2 u_2 \,\alpha \cos^2 x + 2\gamma_4 \cos x \tag{4.8}$$

$$\boldsymbol{O}(\varepsilon^5): \ Nu_5 = \frac{d^2 u_3}{dx^2} - 3\bar{b}^3 u_3 \,\alpha\cos^2 x - 3\bar{b}\alpha u_2^2 \cos x + \beta \,\bar{b}^5 \cos^5 x + 2\gamma_5 \cos x \quad (4.9)$$

$$\boldsymbol{O}(\varepsilon^{6}): \quad Nu_{6} = \frac{d^{2}u_{4}}{dx^{2}} - \alpha \{ 3\bar{b}^{2}u_{4}\cos^{2}x + 6\bar{b}u_{2}u_{3}\cos x - u_{2}^{3} \} - 6\alpha v_{2}v_{3}\cos x + 5\beta u_{2}\bar{b}^{4}\cos^{4}x + 2\gamma_{6}\cos x$$
(4.10)

$$\boldsymbol{0}(\varepsilon^{7}): \quad Nu_{7} = \frac{d^{2}u_{5}}{dx^{2}} - \alpha \{ 3\bar{b}^{2}u_{5}\cos^{2}x + 3\bar{b}u_{2}\cos x(u_{3}^{2} + 2u_{2}u_{4}) + 3u_{2}^{3}u_{3} \} + 5\beta u_{3}\bar{b}^{4}\cos^{4}x + 2\gamma_{7}\cos x$$

$$(4.11)$$

etc.

We shall still use the same orthogonality condition as (3.7). Thus, from (4.5), we get

$$\gamma_1 = 0, \qquad u_1 = 0 \tag{4.12a}$$

From (4.6), we get

$$\gamma_2 = 0, \qquad u_2 = 0 \tag{4.12b}$$

Equation (4.7) simplifies to

$$Nu_3 = \left(2\gamma_3 - \bar{b} - \frac{3\alpha\bar{b}^3}{4}\right)\cos x - \frac{\alpha\bar{b}^3}{4}\cos 3x \tag{4.13}$$

Application of (3.7) in (4.13) yields

$$\gamma_3 = \frac{1}{2} \left(\bar{b} + \frac{\alpha \bar{b}^3}{4} \right) \tag{4.14a}$$

The solution of the remaining equation in (4.13) is

$$u_3 = \frac{\alpha \bar{b}^3}{32} \cos 3x \tag{4.14b}$$

Substituting for u_2 in (4.8) yields

$$\gamma_4 = 0, \qquad u_4 = 0$$
 (4.15)

Substituting for u_2 and u_3 in (4.9) gives

$$Nu_5 = A_9 \cos x + A_{10} \cos 3x + A_{11} \cos 5x \tag{4.16a}$$

where,

$$A_9 = \left(\frac{11\beta\bar{b}^5}{16} + 2\gamma_5 - \frac{3\alpha\bar{b}^5}{128}\right)$$
(4.16*b*)

$$A_{10} = \left(\frac{\beta \bar{b}^5}{4} - \frac{9\alpha \bar{b}^3}{32} - \frac{3\alpha \bar{b}^5}{64}\right), \quad A_{11} = \left(\frac{\beta \bar{b}^5}{16} - \frac{3\alpha \bar{b}^5}{128}\right)$$
(4.16c)

On account of (3.7), we observe that $A_9 = 0$. This yields

$$\gamma_5 = \frac{1}{2} \left(\frac{3\alpha \bar{b}^5}{128} - \frac{11\beta \bar{b}^5}{16} \right) \tag{4.17a}$$

The remaining equation in (4.16a) is solved to get

$$u_5 = -\left(\frac{A_{10}\cos 3x}{8} + \frac{A_{11}\cos 5x}{24}\right) \tag{4.17b}$$

On substituting for relevant terms in (4.10), we obtain

$$\gamma_6 = 0, \qquad u_6 = 0 \tag{4.18}$$

After substituting for terms in (4.11) and simplifying, the equation becomes

$$Nu_7 = A_{12}\cos x + A_{13}\cos 3x + A_{14}\cos 5x + A_{15}\cos 7x$$
(4.19)

where,

$$A_{12} = \left[\frac{15\alpha\beta\bar{b}^{7}}{512} + 2\gamma_{7} + \alpha\left\{\frac{3\bar{b}^{2}A_{9}}{16} - \frac{3\alpha^{2}\bar{b}^{7}}{2048}\right\}\right]$$
(4.20*a*)

$$A_{13} = \left[\frac{9A_9}{8} + \alpha \left\{\frac{3\bar{b}^2 A_9}{16} + \frac{3\bar{b}A_{11}}{48}\right\} + \frac{15\alpha\beta\bar{b}^7}{256}\right]$$
(4.20*b*)

$$A_{14} = \left[\frac{25A_{11}}{4} + \alpha \left\{\frac{3\bar{b}^2 A_{11}}{48} + \frac{3\bar{b}^2 A_9}{16} - \frac{3\alpha^2 \bar{b}^7}{1024}\right\} + \frac{5\alpha\beta\bar{b}^7}{256}\right]$$
(4.20*c*)

$$A_{15} = \left[\left\{ \frac{3\alpha \bar{b}A_{11}}{48} - \frac{3\alpha^3 \bar{b}^7}{4096} \right\} + \frac{5\alpha\beta \bar{b}^7}{512} \right]$$
(4.20*d*)

From the orthogonality condition (3.7) as applied to (4.19), we get

$$\gamma_7 = -\frac{1}{2} \left[\frac{15\alpha\beta\bar{b}^7}{512} + \left\{ \frac{3\bar{b}^2A_9}{16} - \frac{3\alpha^2\bar{b}^7}{2048} \right\} \right]$$
(4.21)

The solution of the remaining equation in (4.19) is

$$u_7 = -\frac{1}{2} \left[\frac{A_{13} \cos 3x}{(41 - 9\lambda)} + \frac{A_{14} \cos 5x}{(313 - 25\lambda)} + \frac{A_{15} \cos 7x}{(1201 - 49\lambda)} \right]$$
(4.22)

From (4.3) and (4.4), we write

$$w(x) = \bar{b}\varepsilon + \frac{\varepsilon^3 \alpha \bar{b}^3 \cos 3x}{32} - \varepsilon^5 \left(\frac{A_{10} \cos 3x}{8} + \frac{A_{11} \cos 5x}{24} \right) - \frac{\varepsilon^7}{2} \left[\frac{A_{13} \cos 3x}{(41 - 9\lambda)} + \frac{A_{14} \cos 5x}{(313 - 25\lambda)} + \frac{A_{15} \cos 7x}{(1201 - 49\lambda)} \right] + \dots$$
(4.23)

Similarly, we have, from (4.4),

$$\lambda \epsilon = \frac{\bar{b}\epsilon^3}{2} \left(1 + \frac{3\alpha \bar{b}^2}{4} \right) + \frac{\bar{b}^5 \epsilon^5}{2} \left(\frac{3\alpha}{128} - \frac{11\beta}{16} \right) - \frac{\bar{b}^2 \epsilon^7}{2} \left[\frac{15\alpha\beta \bar{b}^5}{512} + \alpha \left\{ \frac{3A_9}{16} - \frac{3\alpha^2 \bar{b}^5}{2048} \right\} \right] + \cdots$$
(4.24)

To determine the buckling load λ_S , we employ (3.30), which yields

$$\frac{3\bar{b}\varepsilon_{\mathcal{S}}^{2}}{2}\left(1+\frac{3\alpha\bar{b}^{2}}{4}\right)+\frac{5\bar{b}^{5}\varepsilon_{\mathcal{S}}^{4}}{2}\left(\frac{3\alpha}{128}-\frac{11\beta}{16}\right)-\frac{7\bar{b}^{2}\varepsilon_{\mathcal{S}}^{6}}{2}\left[\frac{15\alpha\beta\bar{b}^{5}}{512}+\alpha\left\{\frac{3A_{9}}{16}-\frac{3\alpha^{2}\bar{b}^{5}}{2048}\right\}\right]=0$$
(4.25)

At this stage, we shall give the result in two levels of approximation. First, if we take only the first two terms in (4.25), we get

$$\frac{3\bar{b}\varepsilon_{S}^{2}}{2}\left(1+\frac{3\alpha\bar{b}^{2}}{4}\right)+\frac{5\bar{b}^{5}\varepsilon_{S}^{4}}{2}\left(\frac{3\alpha}{128}-\frac{11\beta}{16}\right)=0$$
(4.26*a*)

where ε_S is the value of ε at static buckling. This gives

$$\varepsilon_{S}^{2} = \frac{3}{5\bar{b}^{4}} \left(\frac{1 + \frac{3\alpha\bar{b}^{2}}{4}}{\frac{11\beta}{16} - \frac{3\alpha}{128}} \right), \qquad \varepsilon_{S} = \frac{1}{\bar{b}^{2}} \sqrt{\frac{3}{5}} \left(\frac{1 + \frac{3\alpha\bar{b}^{2}}{4}}{\frac{11\beta}{16} - \frac{3\alpha}{128}} \right)^{\frac{1}{2}}$$
(4.26*b*)

Now, on evaluating (4.24) at buckling, where $\lambda = \lambda_S$, we get

$$\lambda_{S}\epsilon = \frac{1}{2\bar{b}^{5}} \left(\frac{3}{5}\right)^{\frac{3}{2}} \left(\frac{1 + \frac{3\alpha\bar{b}^{2}}{4}}{\frac{11\beta}{16} - \frac{3\alpha}{128}}\right)^{\frac{1}{2}} \left[\left(1 + \frac{3\alpha\bar{b}^{2}}{4}\right) - \varepsilon_{S}^{2} \left\{\bar{b}^{4} \left(\frac{11\beta}{16} - \frac{3\alpha}{128}\right) + \varepsilon_{S}^{2} A_{16} \right\} \right]$$
(4.27*a*)

where,

$$A_{16}(\lambda_S) = \left[\frac{15\alpha\beta\bar{b}^5}{512} + \alpha\left\{\frac{3A_9}{16} - \frac{3\alpha^2\bar{b}^5}{2048}\right\}\right]$$
(4.27*b*)

and where (4.27a, b) are evaluated at where $\lambda = \lambda_S$. If we take the three terms in (4.25) then, we can write the whole equation as

$$\varepsilon_{S}^{2} \left[\frac{3\bar{b}}{2} A_{17} + \frac{5\bar{b}^{4} \varepsilon_{S}^{2}}{2} A_{18} - \frac{7\bar{b}^{2} \varepsilon_{S}^{4}}{2} A_{19} \right] = 0$$
(4.28*a*)

where,

$$A_{17} = \left(1 + \frac{3\alpha\bar{b}^2}{4}\right), \quad A_{18} = -\left(\frac{11\beta}{16} - \frac{3\alpha}{128}\right),$$
$$A_{19} = \left[\frac{15\alpha\beta\bar{b}^5}{512} + \alpha\left\{\frac{3A_9}{16} - \frac{3\alpha^2\bar{b}^5}{2048}\right\}\right] \quad (4.28b)$$

Then, we can recast (4.28a) simply as

$$C_1 \varepsilon_S^4 - C_2 \varepsilon_S^2 - C_3 = 0 \tag{4.29a}$$

where,

$$C_1 = \frac{7\bar{b}^2}{2}A_{19}, \quad C_2 = \frac{5\bar{b}^4}{2}A_{18}, \quad C_3 = \frac{3\bar{b}}{2}A_{17}$$
 (4.29b)

The solution of (4.29a) is

$$\varepsilon_{S}^{2} = \frac{5\bar{b}^{2}A_{18}}{7A_{19}} \left[1 - \sqrt{1 + \frac{84A_{17}A_{19}}{25\bar{b}^{6}A_{18}^{2}}} \right]$$
(4.30*a*)
$$\varepsilon_{S} = \bar{b} \sqrt{\frac{5}{7}} \left(\frac{A_{18}}{A_{19}}\right)^{\frac{1}{2}} \left[1 - \sqrt{1 + \frac{84A_{17}A_{19}}{25\bar{b}^{6}A_{18}^{2}}} \right]^{\frac{1}{2}}$$
(4.30*b*)

The static buckling load in this case is determined using (4.24) at $\lambda = \lambda_S$ and using the values of ε_S^2 and ε_S as in (4.30a, b) respectively. This gives

$$\lambda_{S}\epsilon = \frac{\bar{b}\varepsilon_{S}^{3}}{2} \left[\left(1 + \frac{3\alpha\bar{b}^{2}}{4} \right) - \frac{\varepsilon_{S}^{2}}{2} \left\{ \left\{ \left(\frac{11\beta}{16} - \frac{3\alpha}{128} \right) + \bar{b}\varepsilon_{S}^{2} \left\{ \frac{15\alpha\beta\bar{b}^{5}}{512} + \alpha \left\{ \frac{3A_{9}}{16} - \frac{3\alpha^{2}\bar{b}^{5}}{2048} \right\} \right\} \right\} \right\}$$
(4.31)

5. ANALYSIS AND DISCUSSION OF RESULTS

The results (3.34), (4.27a) and (4.31) show mathematical relationship between the Static buckling load λ_S and the imperfection parameter ϵ . Using Q – Basic codes with $\overline{b} = 0.5$, the results obtained from the two methods are shown both on Table1 and Table2 as well as on Figure1 and Figure2. It is clearly shown that the Static buckling load, in each case, decreases with increased imperfection parameter. All results are implicit in the load parameter λ_S and are valid provided the perturbation parameters are small relative to unity. It is pertinent that \overline{b} satisfies the inequality $0 < \overline{b} < 1$.

6. Numerical and Graphical Plots

Table 1: Relationship between the Static buckling load λ_s and the Imperfection parameter, ϵ for $\alpha = 1$, $\beta = 1$ using Eqn. (3.34).

IMPERFECTION	λ_S for $\alpha = 1$, $\beta = 1$
PARAMETER, e	
0.01	0.286212
0.02	0.285966
0.03	0.285721
0.04	0.285478
0.05	0.285236
0.06	0.284995
0.07	0.284756
0.08	0.284519
0.09	0.284283
0.1	0.284048



Figure 1: Graphical Plot of Table 1, showing the relationship between the Static buckling load λ_S and the Imperfection parameter, ϵ for $\alpha = 1$, $\beta = 1$, using Eqn. (3.34).

Table 2: Relationship between the Static buckling load λ_S and the Imperfectio	n parameter, e
for $lpha$ = 1, eta = 1 and \overline{b} = 0. 5, using Eqn. (4.27a).	

IMPERFECTION PARAMETER, ¢	λ_S for $lpha$ = 1, eta = 1, \overline{b} = 0.5
0.01	0.571931
0.02	0.285966
0.03	0.190644
0.04	0.142983
0.05	0.114387
0.06	0.095322
0.07	0.081705
0.08	0.071492
0.09	0.063548
0.1	0.057194



Figure 2: Graphical Plot of Table 2, showing the relationship between the Static buckling load λ_S and the Imperfection parameter, ϵ for $\alpha = 1$, $\beta = 1$ and $\overline{b} = 0.5$, using Eqn. (4.27a).

REFERENCES

- [1] W. B. Fraser and B. Budiansky (1969), The buckling of a column with random initial deflection. J. of Appl. Mech. 36, 232 240.
- [2] J. C. Amazigo, B. Budiansky and G. F. Carrier (1970), Asymptotic analysis of the buckling of imperfect columns on nonlinear elastic foundation, Int. J. Solids Struct., 6, 1341 – 1356.
- [3] J. C. Amazigo (1974), Buckling of stochastically imperfect structures in buckling of structures, IUTAM Symposium, Cambridge, USA, 172 – 182.
- [4] A. M. Reda and G. L. Forbes (2012), Investigation into the dynamic effect of lateral buckling of high temperature / high pressure of offshore pipelines. Proceedings of Acoustics, Paper 83, Australia.
- [5] R. S. Priyardasini, V. Kalyanaraman and S. M. Srinvasan (2012), Numerical and experimental study of buckling of advanced fibre composite cylinder under axial compression. Int. J. of Structural Stability and Dynamics, 12 (4), 1 – 25.
- [6] V. Chitra and R. S. Priyardasini (2013), Dynamic buckling of composite cylindrical shells subjected to axial impulse, Int. Journal of Scientific and Engineering Research, 4 (5), 162 – 165.
- [7] G. J. Mcshane, S. M. Pingle, V. S. Deshpander and N. A. Flock (2012), Dynamic buckling of inclined structures, Int. J. of Solids Structures, 49, 2830 – 2838.
- [8] Z. Kolakowski (2009), Static and dynamic interactive buckling of composite columns, J. of Theoretical and Appl. Mechanics, 47 (1), 177 – 192.

UNDER PEER REVIEW

- [9] Z. Kolakowski (2010), Static and dynamic interactive buckling regarding axial extension mode of thin walled channels, J. of Theoretical and appl. Mechanics, 48 (3), 703 714.
- [10] A. Patil, K. Amol, S. Abdul and A. W. Shaikh (2014), Review of buckling in various Structures like plates and shell, Int. J. of Research in Engineering and technology, 3 (4), 396 402.