#### Hidden oscillations in fractional-order 1 multidimensional chaotic systems 2 3 4 Ismailov Bahram Israfil 5 6 7 8 Azerbaijan State Oil and Industry University, Baku, AZ1010, Azerbaijan Republic The sole author designed, analyzed and interpreted and prepared the manuscript. 9 10 12 ABSTRACT 13 14 In this paper we propose numerical method for the study of localized hidden oscillation in multidimensional fractional chaotic dynamical systems. Implementation of the algorithm is different from the classical method of Aizerman and Kaplan. The reconstructed mapping is presented. 15 Keywords: chaotic system, time series, SSA – algorithm, lifting, Poincare diagram. 16 17 18 **1. INTRODUCTION** 19 20 The implementation of the tasks on the stability of multidimensional chaotic systems of 21 fractional order can manifest hidden oscillation, that are not established after the transition 22 process from the neighborhoods of the stationary states. Here a simple simulation can lead 23 to erroneous results. Therefore, numerous results dealing with mechanisms of the generation of attractors, 24 25 their localization in the phase space, and the evolution of their characteristics where obtained with the use of computer modeling well - known examples of the existence of 26 27 hidden attractor in multidimensional models of automated control systems are given by 28 counterexamples to the Aizerman and Kaplan conjecture, where the unique stable-in-small 29 equilibrium co-exists with an orbital stable cycle [1]. Effectively verified conditions for the existence hidden orbital stable cycles in some 30 class multidimensional systems were obtained in [1]. 31 32 Thus, the is a statement 33 34 2. FORMULATION OF THE PROBLEM 35 Consider the following n-dimensional-fractional-order chaotic system [2] 36 $D^{q}X = F(X, X_{0}, \theta),$ 37 (1)where $X = \left(x_1, x_2, \dots, x_n\right)^T \in \mathbb{R}^n$ denotes the n-dimensional state vector of the original 38 system; $X_0$ - represents the system initial state, $q = (q_1, q_2, ..., q_n)^T \in R^n$ is a set of 39 fractional order of the original system, and $\theta = (\theta_1, \theta_2, \dots, \theta_D)^T \in R^D$ is the value of original 40 system parameters. 41

42 Let the fractional-order derivative of the function f(t) in the Caputo sense is defined 43 as [2]: 44  $D^q f(t) = J^{m-q} f^{(m)}(t).$  (2)

45 Here, q is the fractional order, m is an integer that satisfies  $m-1 \le q < m, f^m(t)$  is

46 the ordinary *m* th derivative of f , and  $J^{\mu}$  is the Riemann-Liouville integral operator of order

47  $\mu > 0$ , defined by

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$$J^{\mu}g(t) = \frac{1}{\Gamma(\mu)} \int_{0}^{t} (t-\tau)^{\mu-1} g(\tau) d\tau,$$
(3)

(5)

49 where  $\Gamma(\cdot)$  denotes the gamma function. A particularly important case in many engineering

50 applications is 0 < q < 1. In this situation, Eq. (2) together with Eq. (3)

51 
$$D_*^q f(t) = \frac{1}{\Gamma(1-q)} \int_0^t (t-\tau)^{-q} f'(\tau) d\tau .$$
 (4)

52 The operator 
$$D_*^q$$
 is often called "*q* th-order Caputo differential operator" and will be  
53 used throughout the paper.

54 Given a fractional-order hyperchaotic systems:

55 Fractional-order Rabinovich-Fabrikant system following [3]:  

$$\dot{x}_1 = x_2 (x_3 - 1 + x_1^2) + \gamma x_1,$$
  
 $\dot{x}_2 = x_1 (3x_3 + 1 - x_1^2) + \gamma x_2,$   
 $\dot{x}_3 = -2x_3 (x_1 x_2 + \alpha),$   
 $\dot{x}_4 = -3x_3 (x_2 x_4 + \delta) + x_4^2,$   
57 where  $\alpha = 0.14, \ \gamma = 1.1, \ -0.01 \le \delta \le 7650.$ 

58 The fractional-order Chen system as follows [4]:

$$\frac{d^{\alpha}x}{dt^{\alpha}} = a(y-x) + w,$$

$$\frac{d^{\alpha}y}{dt^{\alpha}} = bx - xz + cy,$$

$$\frac{d^{\alpha}z}{dt^{\alpha}} = xy - dz,$$

$$\frac{d^{\alpha}w}{dt^{\alpha}} = yz + rw,$$
(6)

60 where a = 35, b = 7, c = 12, d = 3, r = 0.5 and  $\alpha = 0.9$ .

61 Let  $\hat{x}_{1,2,} =_{\alpha} \{x_n\}_{n=0}^N$  is the mapping of the (5-6) hyperchaotic fractional-order and (3) 62 hyperchaotic systems.

# 63 2.1. SSA Algorithm

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We consider a time series  $Y_T = (y_1, \dots, y_T)$ . Fix  $L(L \le T/2)$ , the window length, and let K = T - L + 1 [5].

67 **Step 1.** (*Computing the trajectory matrix*): this transfers a one-dimensional time series 68  $Y_T = (y_1, ..., y_T)$  into the multi-dimensional series  $X_1, ..., X_K$  with vectors 69  $X_i = (y_i, ..., y_{i+L-1}) \in \mathbf{R}^L$ , where K = T - L + 1. The single parameter of the embedding 70 is the window length L, an integer such that  $2 \le L \le T$ . The result of this step is the 71 trajectory matrix  $\mathbf{X} = [X_1, ..., X_K]$ , [5]:

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$$\mathbf{X} = (x_{ij})_{i,j=1}^{L,K} = \begin{pmatrix} y_1 & y_2 & y_3 & \cdots & y_K \\ y_2 & y_3 & y_4 & \cdots & y_{K+1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ y_L & y_{L+1} & y_{L+2} & \cdots & y_T \end{pmatrix}.$$
 (7)

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74 Note that the trajectory matrix **X** is a Hankel matrix, which means that all the 75 elements along the diagonal i + j = const are equal.

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# **Step 2.** Compute the matrix $\mathbf{X}\mathbf{X}^{T}$ .

79 **Step 3.** Compute the eigenvalues and eigenvectors of the matrix  $\mathbf{X}\mathbf{X}^{T}$  and represent 80 it in the form  $\mathbf{X}\mathbf{X}^{T} = P\Lambda P^{T}$ . Here  $\Lambda = diag(\lambda_{1},...,\lambda_{L})$  is the diagonal matrix of 81 eigenvalues of  $\mathbf{X}\mathbf{X}^{T}$  ordered so that  $\lambda_{1} \ge \lambda_{2} \ge ... \ge \lambda_{L} \ge 0$  and  $P = (P_{1}, P_{2},...,P_{L})$  is 82 the corresponding orthogonal matrix of eigen-vectors of  $\mathbf{X}\mathbf{X}^{T}$ .

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84	<b>Step 4.</b> (Selection of eigen-vectors): select a group of $l$ $(1 \le l \le L)$ eigen-vectors
85	$P_{i_1}, P_{i_2}, \ldots, P_{i_l}$ .
86	The grouping step corresponds to splitting the elementary matrices $\mathbf{X}_i$ into several
87	groups
88	and summing the matrices within each group. Let $I=\{i_1,\ldots,i_l\}$ be a group of indices
89	$m{i}_1,\ldots,m{i}_l$ . Then the matrix $\mathbf{X}_I$ corresponding to the group $I$ is defined as
90	$\mathbf{X}_I = \mathbf{X}_{i_1} + \dots + \mathbf{X}_{i_l}.$
91 92	Stop 5 (Pacapetruction of the one-dimensional series); compute the matrix
93	$\tilde{\mathbf{X}} = \ \tilde{\mathbf{x}}_{t}\  = \sum_{i=1}^{t} P_{i} P_{i}^{T} \mathbf{X}_{i}$ as an approximation to $\mathbf{X}$ . Transition to the one-dimensional
94 95	series can now be achieved by averaging over the diagonals of the matrix $\tilde{\mathbf{X}}$ [5]. It is known, the singularly-spectral analysis is effective in a combination with wavelet-
96 97 98	transformation [6]. It is connected by that the signal can have a changing frequency. Further cleaned components related to the trend and noise. After the restoration of a number using wavelet-transform [6].
99	In this paper, for the purpose of localization and reconstruction of abnormal
100	components of fractional dynamic chaotic multidimensional maps, it proposed the use
101 102	singularly-spectral analysis in combination with lifting method [7].
103	stretching's and shifts of one function.
104	The advantage of the lifting scheme is:
105	<ol> <li>the conversion process occurs quickly;</li> <li>the set of wavelet-coefficients, occupies a volume that matches the original data:</li> </ol>
107	<ol> <li>return transformation restores a signal very precisely.</li> </ol>
108	2.2. Lifting schome
109	2.2. Linung scheme
111	Briefly, the mechanism is a follows [7]. Let the original signal $s_j$ contains $2^j$ points.
112	Transformation involves three steps (split-predict-update), which will yield two sets of points
113	$s_{j-1}$ and $d_{j-1}$ .
114	Split
115	From in $s_j$ shape two new not crossed sets. We note that the division of the set into
116	two depends on the type of wavelet. For example, Lazy wavelet distinguishes $\mathit{even}_{j-1}$ and
117	$odd_{j-1}$ samples.
118	Formally it looks as [7]:
119	$(even_{j-1}, odd_{j-1}) = S(s_j).$ (8)
120	Predict
121	Here is calculated the difference between true and predicted values and defines
122	d = odd = p(m, m)
123	$a_{j-1} = oaa_{j-1} - P(even_{j-1}), $ (9)
124 125	where $P$ - the predicting operator.
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### 126 **Update**

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127 On this step, the help of the operator U, calculate coefficients  $s_{i-1}$  [7]:

$$s_{j-1} = even_{j-1} + U(d_{j-1}).$$
(10)

129 The described algorithm of transformation of data lifting-scheme is presented in figure130 [7].131



161 Step 5. Construction Poincare recurrence diagrams.162



# 4. VISUALIZATION OF SIMULATION



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